

EC501 Econometric Methods and Applications

Problem Set 7: Sketch Solutions

Serial Correlation and Dynamic Models

1. (a) By repeated backward substitution:

$$\begin{aligned}
 \epsilon_t &= \rho(\rho\epsilon_{t-2} + u_{t-1}) + u_t \\
 &= \rho^2\epsilon_{t-2} + u_t + \rho u_{t-1} \\
 &= \rho^2(\rho\epsilon_{t-3} + u_{t-2}) + u_t + \rho u_{t-1} \\
 &= \rho^3\epsilon_{t-3} + u_t + \rho u_{t-1} + \rho^2 u_{t-2} \\
 &\quad \vdots \\
 &= \rho^s\epsilon_{t-s} + u_t + \rho u_{t-1} + \dots + \rho^{s-2}u_{t-s+2} + \rho^{s-1}u_{t-s+1} \\
 \text{i.e. } \epsilon_t &= \rho^s\epsilon_{t-s} + \sum_{i=0}^{s-1} \rho^i u_{t-i} \quad (s > 0).
 \end{aligned}$$

- (b) Clearly $E(\epsilon_t) = 0$ while, applying the $var(\cdot)$ operator to $\epsilon_t = \rho\epsilon_{t-1} + u_t$ we obtain

$$\gamma_0 = var(\epsilon_t) = \rho^2 var(\epsilon_{t-1}) + 2cov(\rho\epsilon_{t-1}, u_t) + var(u_t).$$

Now $var(\epsilon_{t-1}) = \gamma_0$, $cov(\epsilon_{t-1}, u_t) = E(\epsilon_{t-1}u_t) = 0$ and $var(u_t) = \sigma_u^2$, so that $\gamma_0 = \rho^2\gamma_0 + \sigma_u^2$, and hence

$$\gamma_0 = \frac{\sigma_u^2}{1 - \rho^2}.$$

Furthermore, $\gamma_s = cov(\epsilon_t, \epsilon_{t-s}) = E(\epsilon_t\epsilon_{t-s})$ can be obtained from the representation in part (a):

$$\begin{aligned}
 E(\epsilon_t\epsilon_{t-s}) &= E\left[\left(\rho^s\epsilon_{t-s} + \sum_{i=0}^{s-1} \rho^i u_{t-i}\right)\epsilon_{t-s}\right] \\
 &= \rho^s E(\epsilon_{t-s}^2) + \sum_{i=0}^{s-1} \rho^i E(u_{t-i}\epsilon_{t-s}) \\
 &= \rho^s \gamma_0 = \frac{\rho^s \sigma_u^2}{1 - \rho^2} = \gamma_s,
 \end{aligned}$$

because $E(u_{t-i}\epsilon_{t-s}) = 0$ for $i = 0, \dots, s-1$.

- (c) It follows from part (b) that $\rho_s = \gamma_s/\gamma_0 = \rho^s$. Simple calculations yield:

ρ	ρ_0	ρ_1	ρ_2	ρ_3	ρ_4	ρ_5
0.1	1.00	0.10	0.01	0.001	0.0001	0.00001
0.9	1.00	0.90	0.81	0.729	0.6561	0.59049

Clearly, the process with $\rho = 0.9$ has the larger correlations and is, therefore, more correlated over time.

2. (a) Clearly, $E(\epsilon_t) = 0$ while

$$\begin{aligned}\gamma_0 = E(\epsilon_t^2) &= E(u_t^2 + 2\lambda u_t u_{t-1} + \lambda^2 u_{t-1}^2) \\ &= E(u_t^2) + 2\lambda E(u_t u_{t-1}) + \lambda^2 E(u_{t-1}^2) \\ &= \sigma_u^2(1 + \lambda^2).\end{aligned}$$

Furthermore,

$$\begin{aligned}\gamma_1 = E(\epsilon_t \epsilon_{t-1}) &= E(u_t + \lambda u_{t-1})(u_{t-1} + \lambda u_{t-2}) \\ &= E(u_t u_{t-1}) + \lambda E(u_{t-1}^2) + \lambda E(u_t u_{t-2}) \\ &\quad + \lambda^2 E(u_{t-1} u_{t-2}) = \lambda \sigma_u^2, \\ \gamma_s = E(\epsilon_t \epsilon_{t-s}) &= E(u_t + \lambda u_{t-1})(u_{t-s} + \lambda u_{t-s-1}) \\ &= E(u_t u_{t-s}) + \lambda E(u_{t-1} u_{t-s}) + \lambda E(u_t u_{t-s-1}) \\ &\quad + \lambda^2 E(u_{t-1} u_{t-s-1}) = 0 \quad \text{for } s > 1.\end{aligned}$$

(b) Obviously $\rho_0 = 1$ while from part (a), $\rho_s = 0$ for $s > 1$, leaving

$$\rho_1 = \frac{\gamma_1}{\gamma_0} = \frac{\lambda \sigma_u^2}{\sigma_u^2(1 + \lambda^2)} = \frac{\lambda}{1 + \lambda^2}.$$

Simple calculations give:

λ	ρ_0	ρ_1	ρ_2	ρ_3	ρ_4	ρ_5
0.5	1.00	0.40	0.00	0.00	0.00	0.00
2.0	1.00	0.40	0.00	0.00	0.00	0.00

This implies that two different parameters in the MA(1) can result in the same autocorrelation structure, which is a potential identification problem. Note, however, that $2 = 1/0.5$, and it is easy to show that any pair of coefficients, λ and $1/\lambda$, will result in identical autocorrelation functions in the MA(1). This generalises to higher-order MA processes.

3. (a) Given that $E(\epsilon_t|X) = 0$ it follows that

$$\begin{aligned}E(b|X) &= \beta + (X'X)^{-1}X'E(\epsilon|X) = \beta, \\ \text{and } E(b) &= E_X(\beta) = \beta,\end{aligned}$$

so that b is unbiased. However, it will not be the BLUE (best linear unbiased estimator) because we are dealing with a generalised linear regression model, for which we know that the GLS estimator is BLUE.

(b) The LM test for first-order serial correlation is most easily carried out by OLS estimation of the equation

$$e_t = x_t' \gamma + \rho e_{t-1} + u_t,$$

and computing the LM statistic as $LM = TR^2$. As $T \rightarrow \infty$, LM converges to a chi-squared random variable with one degree of freedom.

(c) We know that

$$\begin{aligned} y_t &= x'_t \beta + \epsilon_t \quad t = 1, \dots, T, \\ \epsilon_t &= \rho \epsilon_{t-1} + u_t \quad |\rho| < 1, \end{aligned}$$

and therefore $\epsilon_{t-1} = y_{t-1} - x'_{t-1} \beta$. Hence, we have that

$$\begin{aligned} y_t &= x'_t \beta + \rho \epsilon_{t-1} + u_t \\ y_t &= x'_t \beta + \rho (y_{t-1} - x'_{t-1} \beta) + u_t \end{aligned}$$

which can be written as

$$y_t = \gamma y_{t-1} + x'_t \alpha + x'_{t-1} \delta + u_t$$

where $\gamma = \rho$, $\alpha = \beta$, $\delta = -\rho\beta$ and $u_t = \epsilon_t - \rho\epsilon_{t-1}$. The parameter ρ can be estimated by the estimate of γ while the vector β can be estimated by the vector α . For this dynamic model to be equivalent to the original static model with AR(1) errors, the estimate of δ should also be restricted to ensure that $\delta = -\rho\beta$ (this is a non-linear restriction that could be incorporated using appropriate methods, e.g., maximum likelihood).

4. (a) The estimated equation, along with the serial correlation test statistic, are as follows:

Source	SS	df	MS	Number of obs = 200		
Model	1729.75671	1	1729.75671	F(1, 198)	=	1015.73
Residual	337.189254	198	1.70297603	Prob > F	=	0.0000
				R-squared	=	0.8369
				Adj R-squared	=	0.8360
Total	2066.94597	199	10.3866631	Root MSE	=	1.305

y	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
x2	1.011538	.0317391	31.87	0.000	.948948	1.074128
_cons	1.177759	.1923631	6.12	0.000	.7984155	1.557102

Breusch-Godfrey LM statistic: 98.28872 Chi-sq(1) P-value = 3.6e-23

The LM statistic is highly significant, rejecting the absence of first-order serial correlation in the residuals.

(b) The estimates and LM test are as follows:

Source	SS	df	MS			
Model	1887.62844	3	629.209481	Number of obs =	199	
Residual	168.194683	195	.862536837	F(3, 195) =	729.49	
				Prob > F =	0.0000	
				R-squared =	0.9182	
				Adj R-squared =	0.9169	
Total	2055.82313	198	10.3829451	Root MSE =	.92873	

	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
y						
L1.	.7031674	.0506626	13.88	0.000	.6032505	.8030844
x2						
--.	1.01443	.0233042	43.53	0.000	.9684692	1.060391
L1.	-.7501685	.0560993	-13.37	0.000	-.8608077	-.6395292
_cons	.5394993	.1768839	3.05	0.003	.190648	.8883505

Breusch-Godfrey LM statistic: .4563323 Chi-sq(1) P-value = .4993

In the LM test we are unable to reject the null of no serial correlation in the residuals and so this equation appears (at least, based on this evidence) to be consistent with the original regression having a first-order serially correlated disturbance.

(c) The test statistic is below:

$$(1) \quad _b[1.x2] = -_b[1.y]*_b[x2]$$

$$F(1, 195) = 2.14$$

$$\text{Prob} > F = 0.1448$$

The test is therefore unable to reject the hypothesis at the 5% level, thereby adding further support to the possibility that the original regression model has a first-order serially correlated disturbance.

(d) The answer is: yes! The test for serial correlation in the original model rejected the null of no serial correlation; the transformed (dynamic) model showed no evidence of a serially correlated disturbances; and the implied restriction on the coefficients was not rejected. All this suggests that the data is well described by a model of the form $y_t = \beta_1 + \beta_2 x_{t2} + \epsilon_t$ with $\epsilon_t = \rho\epsilon_{t-1} + u_t$.