

# EC951 Lecture 2: Moral Hazard part II

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# Lecture notes 2: Multiple outcomes, MLRP, Signals/Informativeness

**Reading:** L&M 4.5, 4.6

Optional/useful: L&M 4.7

Alt: Milgrom and Roberts ch 7.

## Exercises (pertaining to these notes):

L&M "moral hazard practice questions.pdf" – 1.3, 1.4b and 1.4c M&R "food for thought chapter 7, questions 1 and 2

2004 final, question 1: Agents' compensation should not depend upon observable luck." Explain clearly why this is the case...

## Important reminder:

You **must** read about limited liability on your own (for now).

This is covered in L&M 4.3 for the 2x2x2 type case.

And in L&M 4.5.1 for the multiple outcome case.

For an exercise on this, see "moral hazard practice questions.pdf"; 1.1 (especially part b), 1.3a

Discussion question:

*Why, when the likelihood ratios are different for each level of output, is the structure of the optimal contract 'bang-bang' in the LL/risk neutral case (only one output rewarded), while, in the risk-aversion case several levels of output may be rewarded?*

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- ...or a limited liability constraint

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    - ★ Note L&M's 'number-line' diagram's (e.g., fig. 4.2, 4.3, 4.4 b) for this latter point.

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Outputs occur with probabilities  $[\pi_{10}, \pi_{20}, \pi_{30}, \dots, \pi_{n0}]$  if  $e = 0$  and

$[\pi_{11}, \pi_{21}, \pi_{31}, \dots, \pi_{n1}]$  if  $e = 1$ .

The maximization problem for the principal is given by

$$\max_{t_1, t_2, \dots, t_n} \sum_{i=1}^n \pi_{i1} [S_i - t_i] \quad (1)$$

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Recognizing that  $t_i = h(u_i) = u^{-1}(u_i)$ , we can express P's problem in terms of A's utility from the wage.

... if P wants to minimize the expected wage he also wants to minimize (the expectation of a transformation of) A's surplus. This shows the problem is concave subject to a linear constraint.):

$$\max_{u_1, u_2, \dots, u_n} \sum_{i=1}^n \pi_{i1} [S_i - h(u_i)] \quad (2)$$

Going back to the previous notation, a contract is an n-tuple  $\{t_1, \dots, t_n\}$  or equivalently  $\{u_1, \dots, u_n\}$  for each possible output.

The maximization problem above is subject to PC & IC:

$$\sum_{i=1}^n \pi_{i1} u_i(t_i) - \psi \geq 0 \quad (\text{PC})$$

$$\begin{aligned} \sum_{i=1}^n \pi_{i1} u_i(t_i) - \psi &\geq \sum_{i=1}^n \pi_{i0} u_i(t_i) && (\text{IC}) \\ \implies \sum_{i=1}^n (\pi_{i1} - \pi_{i0}) u_i(t_i) &\geq \psi \end{aligned}$$

(Note: similar to previous notes but with summation operators)

Arguments as in the two output case  $\implies$  both constraints are binding,

$\implies$  Lagrangian:

$$L = \sum \pi_{i1} \times [S_i - t_i] \dots \quad (3)$$
$$+ \mu \left( \sum_{i=1}^n \pi_{i1} u_i(t_i) - \psi \right) + \lambda \left( \sum_{i=1}^n (\pi_{i1} - \pi_{i0}) u_i(t_i) - \psi \right)$$

$$\lambda \geq 0, \mu \geq 0 \text{ (because binding)} \quad (4)$$

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Taking the FOC's w.r.t. the  $t$ 's and rearranging yields (as in L&M section 4.4):

$$\frac{1}{u'(t_i)} = \mu + \lambda \frac{\pi_{i1} - \pi_{i0}}{\pi_{i1}} \forall i$$

for  $i = 1, 2, 3..n$ .

Note that the relative optimal transfers do \*not\* depend on relative quantities. We assume that, given the output function etc, P has already decided to induce high effort. Now what matters is what each output reveals about A's effort.

## Are wages always increasing in output?

$$\frac{1}{u'(t_i^{SB})} = \mu + \lambda \frac{\pi_{i1} - \pi_{i0}}{\pi_{i1}}$$

$\implies$  For  $t_i$  to increase in  $q_i$ ,  $\frac{\pi_{i1} - \pi_{i0}}{\pi_{i1}}$  must increase in  $i$  (i.e., in  $q$ )

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$\implies$  RHS must increase in  $i$  for  $t$  to increase in  $i$

I.e., the likelihood ratio of output under different actions must be monotonically increasing with respect to outputs. Basically, the relative probability of high effort must be higher the higher the output.

$\implies$  the **Monotone Likelihood Ratio Property (MLRP)**.

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- If wages *decrease* in output:
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- But MLRP is a 'rather strong assumption' (L&M)
- Consider a case where effort is 'risky', making spectacularly good and bad outcomes more likely...

## Example where MLRP fails:

$$\pi_{10} = \frac{1}{6}, \pi_{20} = \frac{2}{3}, \pi_{30} = \frac{1}{6},$$
$$\pi_{11} = \pi_{21} = \pi_{31} = \frac{1}{3}$$

$$\frac{\pi_{11} - \pi_{10}}{\pi_{11}} = \frac{1}{2}$$
$$\frac{\pi_{21} - \pi_{20}}{\pi_{21}} = -1$$
$$\frac{\pi_{31} - \pi_{30}}{\pi_{31}} = \frac{1}{2}$$

This is not monotone... so MLRP fails.

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- Thus,  $t_2 < t_1 = t_3$  to induce  $e = 1$  (at the lowest cost according to the previous formula). Not monotonic!
- If agent can destroy output secretly, the contract will have to offer the same reward to  $S_1$  and  $S_2$ , leading to a greater necessary risk-premium for the same incentive.

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Information structure for signals:

	$e = 0$	$e = 1$
$\sigma_1$	$v_{10}$	$v_{11}$
$\sigma_0$	$v_{00}$	$v_{01}$

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$v_{10} = v_{11}$  (implying  $v_{00} = v_{01}$ )  $\implies$  “The signal is uninformative”



Four states:  $y_{11} = \{q_1, \sigma_1\}$ ,  $y_{10} = \{q_1, \sigma_0\}$ ,  $y_{01} = \{q_0, \sigma_1\}$  or  $y_{00} = \{q_0, \sigma_0\}$ .

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By independence of the signal and the stochastic component of output:

$$\pi_{jkl} = p(q_j, \sigma_k | e = l) = p(q_j | e = l) \times p(\sigma_k | e = l) = \pi_{jl} v_{kl}$$

# “Informativeness principle” / Holstrom's sufficient statistic theorem

Consider transfer  $t_{jk}$  for state  $y_{jk}$  (output  $q_j$  signal  $\sigma_k$ ). Previous methods  $\implies$  FOC's:

$$\frac{1}{u'(t_{jk})} = \mu + \lambda \frac{\pi_{jk1} - \pi_{jk0}}{\pi_{jk1}} = \mu + \lambda \frac{\pi_{j1} v_{k1} - \pi_{j0} v_{k0}}{\pi_{j1} v_{k1}} \quad (5)$$

$$v_{k0} = v_{k1} = v_k \rightarrow \frac{1}{u'(t_{jk})} = \mu + \lambda \frac{\pi_{j1} - \pi_{j0}}{\pi_{j1}}. \quad (6)$$

Note no 'k' on right hand side (7)

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Result (obvious?):  $P$  varies wages between states with same output but a different signal if and only if the signal yields some information about the effort chosen.